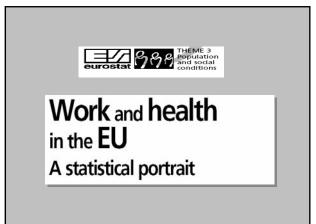
C(777) Marca	DGUV conference on MSD 16th / 17th of October 2009, Institute Work and Health (BGAG) DRESDEN	
(ISC	ernational ergonomics standards D and CEN) and relevant methods isk assessment and management in WMSDs area	
Carlot Garden	Enrico Occhipinti Research Unit "Ergonomics of Posture and Movement" - EPM University of Milan (Italy) Chair IEA TC on Musculoskeletal Disorders	ITÀ UDI KO





PREVALENCE OF WORK REI	ATED HEALTH PROBLEMS
27 EU CO	OUNTRIES
Table 7.1: Percentage of work	kers reporting each
Individual symptom, EU27 (%	
Symptom	
Backache	24.7
Muscular pain	22.8
Fatigue	22.6
Stress	22.3
Headaches	15.5
Irritability	10.5
Injuries	9.7
Sleeping problems	8.7
Anxiety	7.8
Eyesight problems	7.8
Hearing problems	7.2
Skin problems	6.6
Stomach ache	5.8
Breathing difficulties	4.8
Allergies	4.0
Heart disease	2.4
Other	1.6



4° EUROPEAN SURVEY- 2005. PRELIMINARY RESULTS

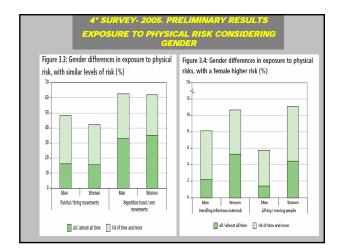
PHYSICAL RISKS

THE SURVEY REVEALS THAT CERTAIN PHYSICAL RISKS STILL PERSIST.

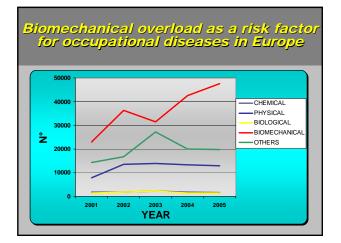
THE PROPORTION OF WORKERS REPORTING REPETITIVE HAND OR ARM MOVEMENTS HAS INCREASED (BY 4%), WITH 62% OF THE WORKING POPULATION REPORTING EXPOSURE FOR 25% OR MORE OF THE TIME;

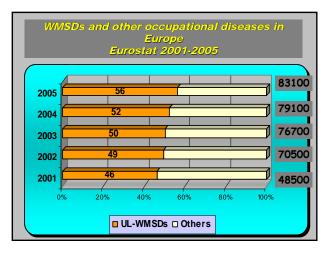
37 % OF WORKERS HANDLES HEAVY LOADS FOR ALMOST 25% OF WORKING TIME

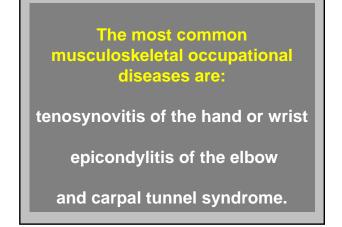
50% OF WORKERS REPORT WORKING IN PAINFUL OR TIRING POSITIONS AT LEAST 25% OF THE TIME.





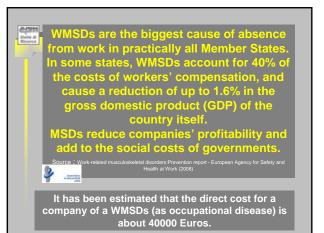




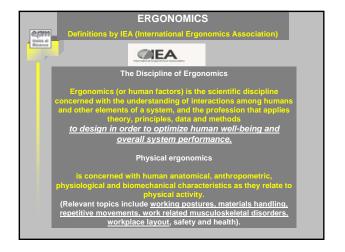


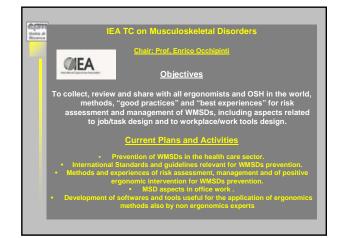
Le "top 3" des maladies professionnelles les plus fréquemment reconnues (2006)				
Pays	Nº1	Nº2	Nº3	
Allemagne	Surdités	Asbestoses et plaques pleurales	Mésothéliomes	
Autriche	Surdités	Maladies de la peau	Asthmes bronchique allergiques	
Belgique (2005)	Maladies ostéo- articulaires	Paralysie des nerfs due à la pression	Surdités	
Danemark (2005)	Maladies de la peau	TMS	Surdités	
Espagne	TMS	Maladies de la peau	Surdités	
France	TMS	Maladies de l'amiante	Lombalgies	
Italie	TMS	Surdités	Maladies respiratoire	
Luxembourg	Maladies Infectieuses	Asbestoses	Canal carpien	
Portugal	TMS	Surdités	Maladies respiratoire	
Suède	TMS	Surdités	Pathologies psychosociales	
Suisse	Surdités	Maladies infectieuses	Maladies de la peau	

	Principales maladies professionnelles reconnues		
F	Haladies	Reconnaissances	En pourcentage du tota
	Tendinites, ténosynovites	10 319	60,6
I	Syndromes de compression des nerfs périphériques dont le syndrome du canal carpien	5 189	12,8
	Dermanoses par agent matériel artificiel	949	5,5
	Hypoacousies ou surdité due au bruit	\$48	3,2
	Hygromas	445	2,6
Г	Autros	2 560	15,0
L			
	Total	17 010	10
	Tetal		
	Tetal Reconnues avec arrêt et indemnisation Malgase	17 010 Reconnaissances 7 307	10 En pourcentage du tess
	Tetal Reconnues avec artist at indemnisation Materian Indefinition Ind	Reconnaissances	En pourcentage du tata
	Tetal Reconnues avec arrêt et indemnisation Malgase	Reconnaissances 7 30?	En pourcentage du tota 63,44
	Tetal Reconnues avec arrêt et indemnisation Malgdae Androites, Vinosynovites Syndrmie du compression des nerts pérghériques dont le syndrome du canul capen	Reconnaissances 7 307 1 504	En pourcentage du tata 63,41 13,01
	Test Reconnues avec arist et indemnisation Malgidee Windnies, Montynowies Sydome du compression des neris pérghéniques dont le syndrome du canal carpan Rymones par agent material arificial	Reconnaissances 7 307 1 504 644	En pourcentage du-tage 63,41 13,01 5,51
	Total Reconnues avec arrêt et îndemnîsation Naldae Syndome, kinospovites Syndome du compressen des meti përghënges deri le syndome du canal capen Remistre par agen material artificiel Regionai	Reconnaissances 7 307 1 504 644 313	En pourcentage du-tate 63,41 13,01 5,9 2,7









Ergonomics standards : aims
Ergonomically designed work systems enhance safety, improve human working and living conditions and counteract adverse effects on human health.
Also they usually improve the operator-machine system performance and reliability.
Applying ergonomics to the design of work systems, ensures that human capabilities, skills, limitations and needs, as well as technological and economic effectiveness and efficiency are taken into account.



COMMISSION ASKS WORKERS AND EMPLOYERS WHAT ACTION SHOULD BE TAKEN TO COMBAT MUSCULOSKELETAL DISORDERS

Brussels, 12 November 2004.

The European Commission is seeking the views of workers' and employers' representatives on how best to tackle the growing problem of musculoskeletal disorders (MSD). These ailments, which include back pain and repetitive strain injury, are the biggest health and safety problem facing European workers today. Studies show that they affect over 40 million workers in all sectors across the EU and account for 40 to 50 per cent of all work-related ill-health. They are costing employers across the EU billions of euros. The problem is eroding Europe's competitiveness and leading to losses of 0.5 to 2 per cent of GNP each year.

SECOND STAGE OF CONSULTATION OF THE SOCIAL PARTNERS ON WORK-RELATED MUSCULOSKELETAL DISORDERS (14 MARCH 2007)

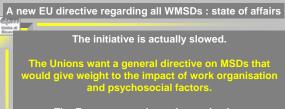
The Commission is considering proposing a new legislative initiative addressing all significant risk factors of work-related musculoskeletal disorders .

This new legislative instrument would take the form of an individual directive.

The envisaged directive would cover all major work-related musculoskeletal disorders.

The envisaged directive would also incorporate the provisions of bot Directive 90/269/EEC and Directive 90/270/EEC.

The envisaged directive would be supplemented by other nonregulatory initiatives.



The European employers' organisation, Businesseurope, is against it and ask for a sectorial approach and the development of non-binding schemes like awareness-building and exchanges of "good practice".

The Commission would like to favour an overall approach that combines regulatory and non-regulatory measures.

International technical standards for WMSDs prevention

C.(3999 Unità di Ricarca

> Actual ergonomics standards (in physical ergonomics area) could be useful to enforce principles, requirements and criteria given by primary European social legislation.

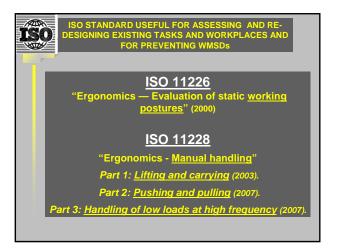
This could happen both in relation to:

 general principles in the framework directive 89/331/EEC (i.e with reference to manual repetitive job)

• existing particular directives (i.e 90/269/EEC on manual handling of loads)

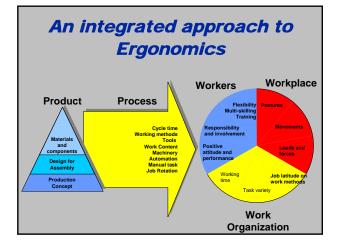


	KPLACES A	FUL FOR DESIGNING
	WMSDs	
STANDARD	NUMBER	PHYSICAL PARAMETERS
Interaction between task and workplace design	EN 614-2	General requirements
Anthropometric requirements for the design of workstation at machinery	EN ISO 14738	Anthropometric requirements
Manual handling of objects associated with machinery	EN 1005-2	Manual handling of loads
Recommended force limits for machinery operation	EN 1005-3	Force limits
Evaluation of working postures in relation to machinery	EN 1005-4	Postures and movements
Repetitive handling at high frequency	EN 1005-5	Action frequency
Those standards specify ergo machinery and related tasks/		ney are generally compulsor









EN 614-2 MIC DESIGN PRINCI

ERGONOMIC DESIGN PRINCIPLES: INTERACTIONS BETWEEN THE DESIGN OF MACHINERY AND WORK TASKS

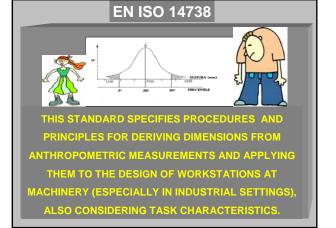
This European Standard helps the designer in applying ergonomics principles to the design of machinery, focusing especially on the interaction between the design of machinery and work tasks.

The designer shall ensure that ergonomics characteristics of well-designed work tasks are fulfilled.

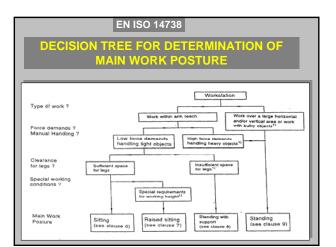
These characteristics shall be pursued <u>by designing</u> <u>machinery and work tasks in</u> <u>interaction.</u>

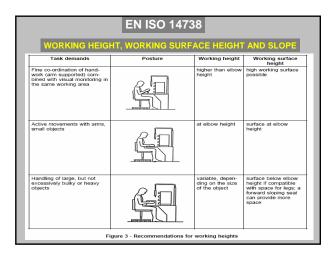
EN ISO 14738

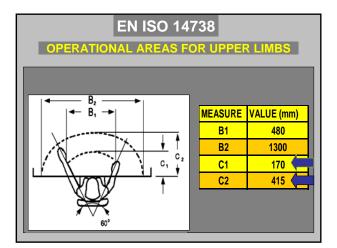
ANTHROPOMETRIC REQUIREMENTS FOR THE DESIGN OF WORKSTATIONS AT MACHINERY

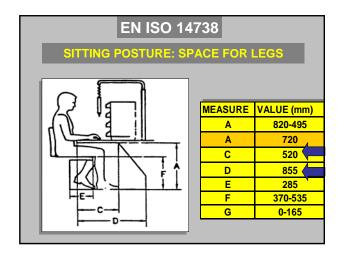


EN ISO 14738 ESIGN OF WORKSTATIONS AT MACHINERY SHALL BE BASED ON AN ANALYSIS OF TASK REQUIREMENTS INCLUDING SEVERAL ELEMENTS: - time aspects; - size of working are aand of objects to be handled; - force and action demands; - dynamic body measurements; - dynamic body measurements; - co-ordination and stability demands; - visual demands; - need for communication; - frequency and duration of body, head and limb movements; - need to move between workstations; - the possibility for adopting different postures











EN 1005 -2 RISK ASSESSMENT BASED ON NIOSH METHOD FOR LIFTING (RNLE) RISK INDEX = LOAD REALLY HANDLED RECOMMENDED LOAD RI < 0,85: the risk is tolerable (green).</td> 0,85 < RI < 1,0: significant risk exists (yellow).</td> RI >1,0 : a definite risk exists and redesign is necessary.

Field of	M _{ref} [kg]	Percentage of			Population group		
application		F and M	Females	Mates			
Domestic use ^a	5	Data not available			Children and the elderly	Total population	
	10	99	99	99	General domestic population		
Professional use (general) ^b	15	95	90	99	General working population, including the young and old	General working population	
	25	85	70	90	Adult working population		
Professional use (exceptional) ⁶	30 35 40	Data not	avallable		Special working population	Special working population	
					d as a general reference mass in the risk : nce mass should be lowered to 5 kg.	assessment. If childrer	
⁹ When designing a	machine for	professiona	il use, a refe	erence mass	of 25 kg should not be exceeded in gene	ral.	
exceptional circums are not sufficiently a	tances whei idvanced). U	e the refere Inder these	nce mass m special con	night exceed ditions other	ties or reduce the risks to the lowest possi 125 kg (e.g. where technological developm measures have to be taken to control the or the intended operator group).	nents or interventions	

EN 1005-3



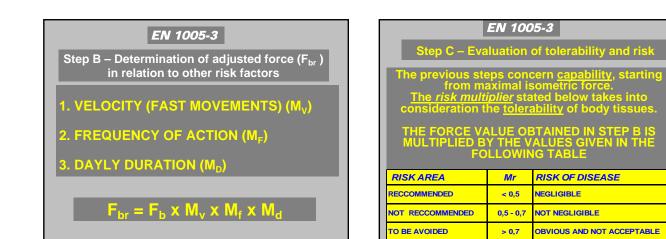
RECOMMENDED FORCE LIMITS FOR MACHINERY OPERATION

Step A : Determination of basic force

Step B : Determination of adjusted force in relation to other risk factors

Step C : Evaluation of tolerability and risk.

	Step A – Basic		
	Activity	Professional use F _B in N	Domestic use F _B in N
	Hand work (one hand):		
	Power grip	250	184
	Arm work (sitting posture, one arm):		
in out	- upwards	50	31
	- downwards	75	44
	- outwards	55	31
	- inwards	75	49
	- pushing		
9 4	 with trunk support 	275	186
(h) I	 without trunk support 	62	30
down	- pulling		
	 with trunk support 	225	169
	 without trunk support 	55	28
9	Whole body work		
1	(standing posture):		
Ka	- pushing	200	119
	- pulling	145	96
	Pedal work (sitting posture,		
	with trunk support):		
	- ankle action	250	154
17ml	- leg action	475	308



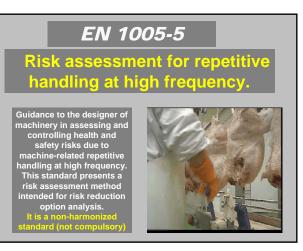
	– 1005-4 JNK – FLEXION / EX ⁻		
	STATIC POSTURE	MOVEN LOW FREQ. (<2 min.)	MENTS HIGH FREQ. (> min.)
ľ	ACCEPTABLE	ACCEPTABLE	ACCEPTABLE
ll°	CONDIZION. ACCEPTABLE(A)	ACCEPTABLE	NOT ACCEPTABLE
III°	NOT ACCEPTABLE	CONDIZION. ACCEPTABLE(C)	
IV°	CONDIZION. ACCEPTABLE (B)	CONDIZION. ACCEPTABLE (C)	NOT ACCEPTABLE

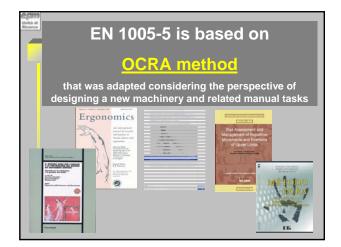


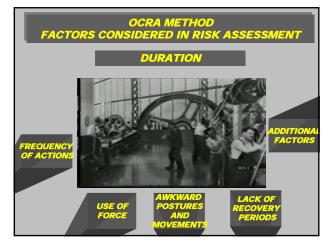
EN 1005-4

VALUATION OF WORKING POSTURES AND MOVEMENTS IN RELATION TO MACHINERY

Dur:

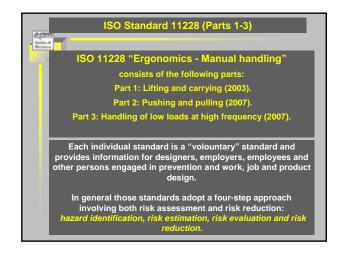


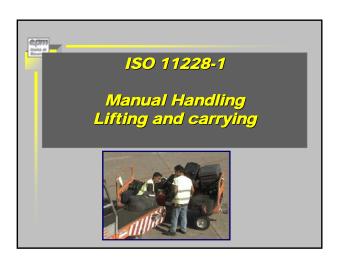


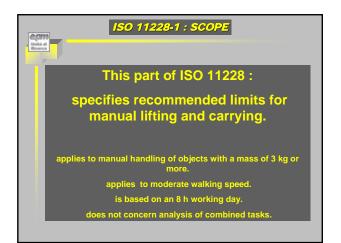


OCRA I	OCRA INDEX CLASSIFICATION (EN 1005-5)					
ZONE	OCRA RISK INDEX	RISK EVALUATION				
GREEN	UP TO 2,2	ACCEPTABLE				
YELLOW	2,3 - 3,5	CONDITIONALLY ACCEPTABLE				
RED	FROM 3,6	NOT ACCEPTABLE				

	EN 1005 - 5 ANNEXES	
Se	veral annexes (A to H) explain how to apply the C method for the purpose of the standard	OCRA
Annex	A (informative) Identification of technical action Examples for identifying and counting technical actions	
	B (informative) Posture and types of movements	
	C (informative) Force	
C.1	General	
C,2	Procedure 2 – A psychophysical approach using the CR-10 Borg scale D (informative) Association between the OCRA index and the occurrence of Upper Li	
D.1 D.2	Work-related Musculo-Skeletal Disorders (UL-WMSDs): criteria for the classification and forecast models. General OCRA Index values, exposure areas and consequent actions.	of results
Annex	E (informative) Influence of recovery periods pattern and work time duration in detern the overall number of reference technical actions within a shift (RTA) and, consequer OCRA index.	tly, the
Annex	F (informative) An application example of risk reduction in a mono-task analysis	
F.1	Foreword	
F.2	General: technical characteristics of the task	
F.3	Hazard identification	
F.4	Method 1	
F.5	Method 2	
Annex	G (informative) Definition and quantification of additional risk factors	
Annex	H (informative) Risk assessment by Method 2 when designing "multitask" jobs	
H.1	OCRA index calculation when two or more repetitive tasks should be assessed	
H.2	An application example: assessing repetitive tasks at a machinery	
H.3	Multi-tasks analysis	
H.4	Conclusion	
Annex	ZA (informative) Relationship between this European Standard and the Essential Requirements of EU Directive 98/79/EC	
Distant	praphy	







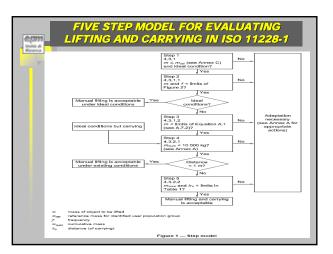
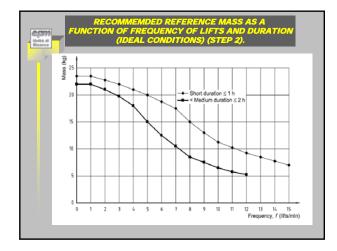


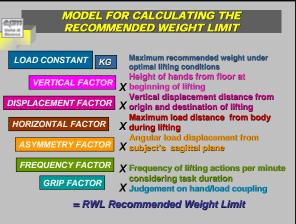
Table C.1 — Reference mass (m _{ref}) for different populations						
Field of m _{ref} Percentage of user population protected Population group						
application	kg	F and M ^a	F	м		•
Non-	5	Data	not availa	able	Children and the elderly	Total constants
occupational use	10	99	99	99	General domestic population	Total population
	15 20 23	95	90	99	General working population, including the young and old	General working popula
Professional	25	85	70	95	Adult working population	
use	30					
	35 40	5	See NOTE		Specialized working population	Specialized working population under spec circumstances
lowest possible ler developments or is must be given to	vels, there intervention the educa	may be excep s are not suffi ation and trai	ciently advi ining of the	mstances anced). In t e individua	 made to avoid manual-handling as where the reference mass may exce- hese exceptional circumstances, incl il (e.g. specialized knowledge conc es of the individual. 	ed 25 kg (e.g. where technol reased attention and conside
a F: Female, M	: Male					

ep Units Rices	ISO 11228-1 The following specificat proposed considering a	
	Working population by gender and age	Reference mass (mref)
	Men (18-45 years old)	25 Kg
	Women (18-45 years old)	20 Kg
	Men (<18 o >45 years old)	20 Kg
	Women (<18 o >45 years old)	15 Kg
	NOTE 1: 23 kg is included	in the 25 kg mass.







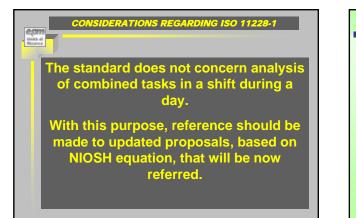


$\begin{tabular}{ c c c c c c c c c c c c c c c c c c c$	Carrying Carrying distance frequency		neral working Cumulative mas		
10 15 750 6 000 5 kg + 3 breaswing 10 2 30 1 500 10 000 10 kg + 0.6 stream 10 2 30 1 500 10 000 6 kg + 0.6 stream 4 4 60 3.000 10 000 6 kg + 2 breaswing 2 0 75 4 500 10 000 6 kg + 2 breaswing 2 0 75 4 500 10 000 6 kg + 1 breaswing 2 0 75 4 500 10 000 0 4 gg + 1 breaswing 1 0 120 7 200 10 000 9 kg + 1 breaswing 1 0 120 7 200 10 000 9 kg + 1 breaswing 1 0 120 7 200 10 0000 9 kg + 1 breaswing NOTE1 in the calculation of the cumulative masks, a inference mask of 15 kg and a breaswing of 15 breaswing 15 kg + 1 breaswing NOTE2 The breaswing breaswing of the cumulative masks, a inference mask of 15 kg and a breaswing of 15 breaswing 15 kg + 1 breaswing	Senas		100 gradest		Examples of product #
Image: state of the s	m min-1	kg/min	kg/h	kg/8 h	
Image: 10 model Image: 12 model Image: 12 model Image: 12 model 10 2 30 1 500 10 000 6 kg = 0.8 model 4 4 60 3 000 10 000 6 kg = 1 model 2 0 75 4 500 10 000 6 kg = 1 model 2 0 75 4 500 10 000 0.9 g = 1 model 1 0 120 75 4 500 10 000 0.9 g = 1 model 1 0 120 7 200 10 000 0.9 g = 1 model 25 kg = 1 model 2011 1 0 120 7 200 10 000 0.9 g = 1 model 2012 10 120 7 200 10 000 0.9 g = 1 model 15 model 2015 1 10 model 10 model 10 model 10 model 10 model 2016 1 10 model 10 model 10 model 10 model	20 1	15	750	6 000	5 kg × 3 times/min
10 2 30 1 500 10 000 8 kg = 6 timesing 15 kg = 6 timesing 26 kg = 1 timesing 26 kg = 1 timesing 26 kg = 1 timesing 26 kg = 1 timesing 27 kg 4 4 60 3 000 10 000 5 kg = 1 timesing 26 kg = 1 timesing 27 kg = 1 timesing 28 kg	1 1				15 kg × 1 time/min
Image: state of the s					25 kg × 0,5 time/min
4 60 3.000 100.000 0.89g - 1.8mm/sm 4 4 60 3.000 10.000 0.89g - 1.2 transitivity 2 5 7.5 4.500 10.000 6.8g - 1.8 mm/sm 2 5 7.5 4.500 10.000 6.8g - 1.8 mm/sm 1 8 120 7.200 10.000 6.8g - 1.8 mm/sm XOTE 1 10 8.0 1200 7.200 10.000 6.8g - 1.8 mm/sm XOTE 1 10 8.0 1200 7.200 10.000 6.8g - 1.8 mm/sm XOTE 1 10 8.0 1200 7.200 10.000 6.8g - 1.8 mm/sm XOTE 1 10 8.0 10.000 6.8g - 1.8 mm/sm 2.8 g - 1.8 mm/sm XOTE 1 10.000 10.000 10.000 15.9 mm/sm 10.8 mm/sm	10 2	30	1 500	10 000	5 kg × 6 times/min
4 4 60 3.000 10.000 5.92 to 2 to summing 15.82 to 2 to 3.000 2 6 7.5 4.500 10.000 6.92 to 3.000 2 6 7.5 4.500 10.000 6.92 to 3.000 1 8 120 7.200 10.000 1.52 to 3.000 1 8 120 7.200 10.000 1.52 to 3.000 0.51 to 3.000 1.52 to 3.000 7.200 10.000 1.52 to 3.000 2011 to 3.000 1.52 to 3.000 1.52 to 3.000 1.52 to 3.000 1.52 to 3.000 2012 to 3.000 1.52 to 3.000 <td></td> <td></td> <td></td> <td></td> <td>15 kg × 2 times/min</td>					15 kg × 2 times/min
Image: second					25 kg × 1 time/min
2 0 75 4.500 10.000 6.8g - 1. Benows 2 0 75 4.500 10.000 6.8g - 1.8 Sensors 1 0 120 7.200 10.000 6.8g - 1.8 Sensors 1 0 120 7.200 10.000 6.9g - 1.8 Sensors 25 10 100 6.9g - 1.9 Sensors 25.8g - 1.8 Sensors 25.8g - 1.8 Sensors 2015 10 100 10.9 Sensors 1.9 Sensors 25.8g - 1.8 Sensors 2016 10 100 10.9 Sensors 1.9 Sensors 1.9 Sensors 1.9 Sensors 2016 100 10.9 Sensors 1.9 Sensors 1.9 Sensors 1.9 Sensors 2016 100 100.9 Sensors 1.9 Sensors 1.9 Sensors 1.9 Sensors 2016 100 100.9 Sensors 1.9 Sensors 1.9 Sensors 1.9 Sensors	4 4	60	3 000	10 000	5 kg × 12 times/min
2 0 75 4 500 10 000 9 sg = 15 timestra 15 kg = 5 timestra 25 kg = 15 timestra 10 000 9 sg = 15 timestra 10 000 9 sg = 15 timestra 10 kg = 15 timestra 15 timestra 15 kg = 15 timestra 15	I				15 kg × 4 times/min
1 8 120 7 200 10 000 5 kg = 15 mmesm 1 8 120 7 200 10 000 5 kg = 15 mmesm 10 1 8 120 7 200 10 000 5 kg = 15 mmesm 10 11 11 mes constation of the cumulative mass, a inference mass of 15 g and a frequency of 25 mesmins 10 kg = 15 mmesm 10 12 11 mesmins and offing and nazuli carring shoot news exceeded not 2000 balts, whethere is the 1800 bal					25 kg × 1 time/min
1 0 120 7 000 100 000 0.5g - 1 terrorism 1 0 120 7 000 100 000 0.5g - 1 terrorism 15 kg = 6 terrorism 25 kg - 1 terrorism 25 kg - 1 terrorism 25 kg - 1 terrorism 2011 1 1 the calculation of the cumulative mask, a interestic mask of 15 kg and a flequency of carryog of 15 terrorism. 25 kg - 1 terrorism 2012 1 25 terrorism and provide mask of terrorism and terrorism mask of 15 kg and a flequency of 15 terrorism. 25 kg - 1 terrorism 2012 1 10 terrorism and terrorism mask of 15 terrorism. 25 kg - 1 terrorism	2 5	75	4 500	10 000	5 kg × 15 times/min
1 8 120 7 200 10 8000 5 kg = 15 temps/m 15 kg = 6 temps/m 15 kg = 6 temps/m 16 temps/m 16 temps/m 5 kg = 16 temps/m 15 kg = 1 temps/m 16 temps/m 16 temps/m 10 temps/m					15 kg × 5 times/min
15 kg = 8 threating 15 kg = 8 threating 25 kg = 1 threating 15 kg and a beganized of 15 kg and a beganized of 15 kg and a beganized of 15 threating 15 kg = 10 threating 15					25 kg × 1 time/min
EDTE 1 In the classification of the cumulative mass, a reference mass of 15 kg and a frequency of carrying of 15 treatmin a the general working population. DTE 2 - The total cumulative mass of through and manual carrying should never exceed 10 000 bottys, writehere is the data	1 8	120	7 200	10 000	5 kg × 15 times/min
EOTE 1 In the calculation of the cumulative mass, a reterence mass of 15 kg and a frequency of carrying of 15 timesmin a the general working copulation.	I				15 kg × 8 times/min
he general working population. KOTE 2 The total cumulative mass of lifting and manual carrying should never exceed 10 000 kg/day, whichever is the dat					25 kg × 1 time/min
NOTE 2 The total cumulative mass of lifting and manual carrying should never exceed 10 000 kg/day, whichever is the day	OTE 1 In the calculation of the o	unulative mass, a	reference mass of 1	15 kg and a frequency	of carrying of 15 times/min are
	OTE 2 The total cumulative mas	s of lifting and ma	nual carrying should	I never exceed 10 00	0 kg/day, whichever is the daily
NOTE 3 23 kg is included in the 25 kg mass.		5 kg mass.			

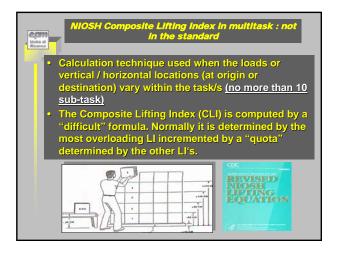
Risk classification and risk reduction
Risk classification is yes/not type.
At every step, if the recommended limit for manual handling is exceeded, then a risk is presumed and the task should be adapted.
Risk reduction can be achieved by minimizing or excluding hazards resulting from the task, the object, the workplace, the work organization or the environmental conditions.
Health surveillance should be provided by the employer with respect to work-related risks.
Technical means of reducing risk should be provided, and complemented with information and appropriate training with respect to work-related risks.

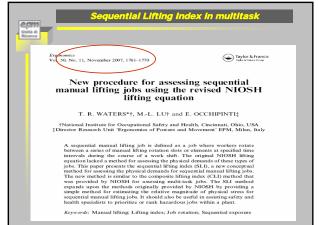
eiam	Interp		ing Index (<i>mA/mR</i>) oposals)	Values
Ricerca	Lifting Index Value	Exposure level	Interpretation	Consequences
	LI ≤ 0,85	Acceptable; No risk	Exposure is acceptable Lifting conditions accommodate > 90% of males and females, including younger and older. (Green zone)	Acceptable: no consequences
	0,85 < LI < 1,0	Borderline or very very low exposure	Exposure is acceptable for most members of reference working population but a significant part of it could be exposed to a very low risk level. (Yellow zone)	If possible, improve structural risk factors or take other organizational measures
	1,0 < LI < 2,0	Risk present; low level	A significant part of adult industrial working population could be exposed to a low risk level (Red-light zone)	Redesign tasks and workplaces according to priorities
	2,0 < LI < 3,0	Risk present; significant level	An increased part of adult industrial working population could be exposed to a significant risk level. (Red zone)	Redesign tasks and workplaces as soon as possible
	LI > 3,0	Risk present; high level	Absolutely not suitable for most working population. (Very red - or violet - zone).	Redesign tasks and workplaces immediately

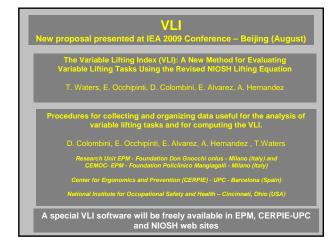
C.C.T.T. Unità d Ricente	CONSIDERATIONS REGARDING ISO 11228-1
	In several contexts, the standard is not "fully" applicable.
	In the healthcare sector, patient' handling assessment could hardly be achieved by methods proposed in the standard.
	ISO TC 159 (and CEN) recently launched the proposal of a Technical Report on "manual handling of people in the healthcare sector"
	<u>(ISO-CD 12296).</u>
	Its publication is foreseen in two years.

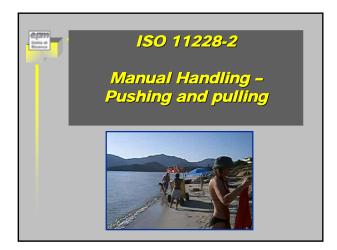


DEFINITIONS OF MANUAL HANDLING TAS	
4 types of working tasks involving MANUAL LIFTING can be in	_
TYPE OF MANUAL LIFTING TASK	RISK INDEX
1.MONO TASK that is task involving the lifting of only one (kind of) object (with the same load) using always the same posture (body geometry) between origin and destination .	LI
 COMPOSITE TASK (ex multitask) when lifting objects of one kind only according to different geometries (collection and positioning on shelves placed at several heights and/or depth levels). Practically each geometry takes the name of SUBTASK. 	CLI
3. VARIABLE TASK when lifting several objects with different weights on shelves placed at different heights and/or depth levels. Each different weight category and each different geometry takes the name of SUBTASK.	VLI
 SEQUENTIAL TASK where workers rotate between a series of single or multi- task lifting rotation slots during a work shift. 	SLI

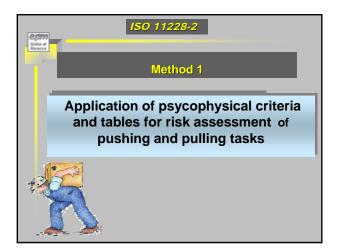




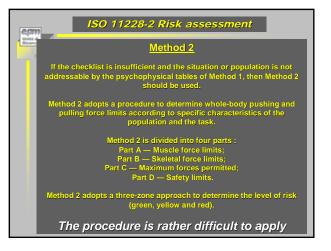


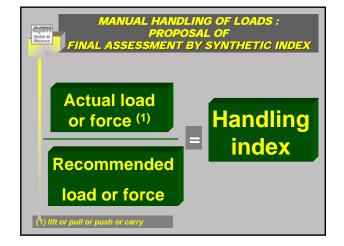


ISO 11228-2 This part of ISO 11228 provides methods for identifying the potential hazards and risks associated with whole-body pushing and pulling. Pushing and pulling, as defined in this part of ISO 11228, is restricted to the following: • whole-body force exertions (i.e. while standing/walking): • actions performed by one person • forces applied by two hands; • forces used to move or restrain an object; • forces applied in a smooth and controlled way: • forces applied without the use of external support(s); • forces applied on objects located in front of the operator; • forces applied in an upright position (not sitting).

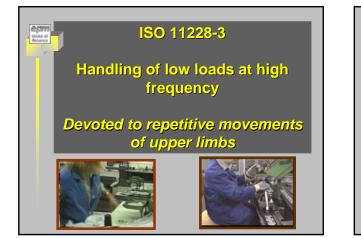


								Tat	le A.5								
			1	'wo-ha	nded j	oushin	g — M	aximu		ptable N	initiəl	force -	- 90 %	of po	pulatio	n	
Har hei								Free	uency	of pus	hing						
		10/1	min	5/m	nin	4/1	nin	2,5	min	1/m	nin	1/2	min	1/5	min	1/	8h
c	m	0,166	7 Hz	0,083	3 Hz	0,06	57 Hz	0,04	2 Hz	0,016	7 Hz	0,008	33 Hz	0,003	33 Hz	3,5 × 1	10-5 H
m	f	m	f	m	f	m	f	m	f	m	f	m	f	m	f	m	f
								2 m	pushir	ng dist	ance						
144	135	200	140	220	150					250	170			260	200	310	220
95	89	210	140	240	150					260	170			280	200	340	220
64	57	190	110	220	120					240	140			250	160	310	180
								Та	ble A.	8							
			τv	ro-han	ded pi	rshing	— Max	imum		table s	ustain	rd forc	e — 90	% of p	popula	tion	
	ight							Fre	quency	ofpu	shing						
		10	/min	51	min	4	min		/min		min	1/2	min	1/5	imin	1/	8h
	cm	0,16	67 Hz	0,08	33 Hz	0,06	67 Hz	0,04	2 Hz	0,01	67 Hz	0,00	83 Hz	0,00	33 Hz	3,5×1	10 ⁻⁶ H
m	f	m	f	m	f	m	f	m	f	m	f	m	f	m	f	m	f
								2 m	pushi	ng dist	lance						
144	135	100	50	130	80					150	100			180	110	220	140
144		100	50	130	70					160	90			190	100	230	130
95	89	1.00	1.00	100	1.0					-							_







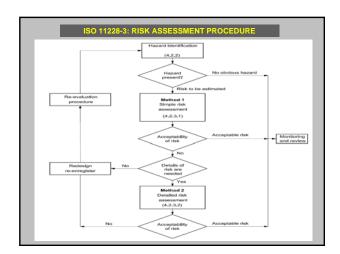


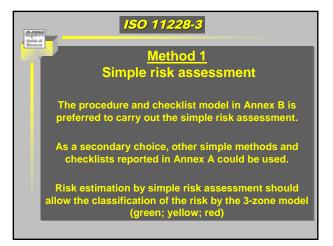
REFERENCE MODEL IN ISO 11228-3

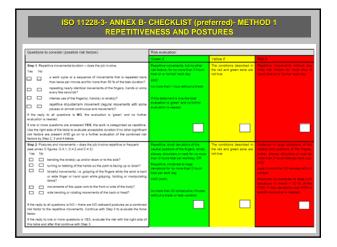
Exposure Assessment of Upper Limb Repetitive Movements: A Consensus Document

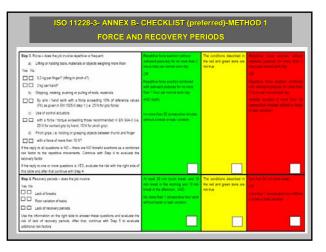
Developed by the Technical Committee on Musculoskeletal Disorders of the International Ergonomics Association (IEA) and endorsed by the International Commission on Occupational Health (ICOH)

COLOMBINI D, OCCHIPINTI E, DELLEMAN N, FALLENTIN M, KILBOM A, GRIECO A: Exposure assessment of upper limb repetitive movements: a Consensus Document. In W.Karwowski (Ed): International Encyclopaedia of Ergonomics and Human Factors. London:Taylor and Francis, 2001:52-66.



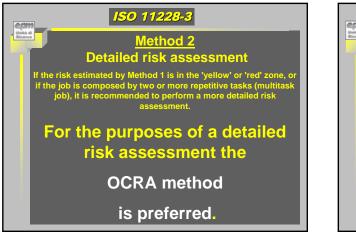


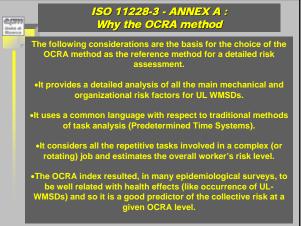


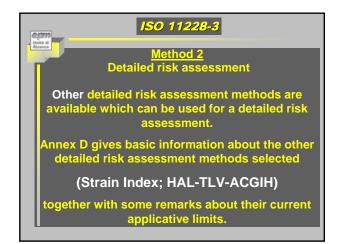


ADDITIONAL FACTOR	S (INCLUDING PSYCHOSOCIAL)
Step 5. Additional risk factors Additional physical factors: does the repetitive job involve: Yee. No.	If additional factors are present these should be considered after the risk factors of Step 1 – 4 have been deal with Note: evaluate static postures/sturation use ISO 11220
Constraints and service and services an	Note Large one of measured P way logit dividuals (see max ROE) are provided 1 is imported to dividual and the second and the s
Locked or fixed postures (bad design of tools or workplaces, lack of specie) Homomering, shock or forces with rapid build-up? Hap precision work combined with force?	
Comparison of the set of the	

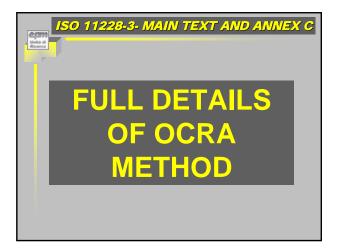
	OTHER	TOOLS USEFUL FOR METHOD	1	
Table	A.1 — Non-ext	austive list of main methods for risk asses movements/exertions at high frequency	sment of repe	lilive
Met	bod	Main characteristics	Kind of output	Body part
OWAS	Ref. [26]	Analysis of postures of different body segments; it also considers their frequency during a work shift.	Quantitative	Whole body
RULA	Ref. [34]	Rapid coded analysis of static and dynamic postures; it also considers force and action frequency; the result is an exposure score that drives to the kind of preventive measures to be taken.	Quantitative	Upper limb
REBA	Ptef. [10]	Similar to RULA (checklist), it considers all body segments while also taking into account manual handling of loads.	Quantitative	Whole body
PLIBEL*	Ref. (27)	Checklist for the identification of different risk factors for different body segments; it considers awkward postures, movements, equipment and other organizational aspects.	Quantitative	Whole body
Strain Index	Ref. [35]	Detailed method (monotask) that considers the following risk factors: intensity of exertion, duration of exertion per cycle, efforts per minute, hand/wrist posture, speed of work, and duration of task per day.	Quantitative	Distal uppe limbs
QEC *	rter. (51)	Quick method for estimating the exposure level. It considers different postures, force, load handled, duration of task with hypothesized scores for their interaction,	Guantitative	Whole body
OSHA checklist ^a	Ref. [45]	Checklist proposed during the development of the OSHA standard (vithdrawn), it considers repetitiveness, ankward postures, force, some additional factors and some organizational aspects.	Quantitative	Upper limbs
HAL/TLV ACGIH	Ref. [1]	Detailed method (for monotask handwork lasting almost 4 h per shift) mainly based on the analysis of frequency of actions (in relation to duty cycle) and of peak force; other main factors are generically considered.	Quantitative	Upper limb
Upper limb expert tool "	Mef. (28)	Screening method evaluating the "work load", it considers repetition, force, awkward postures, task duration and some additional factors.	Semi- quantitative	Upper limb
OGRA Index	Plof. [11]. [36]	Detailed method that considers the following risk factors: frequency of technical actions, repetitiveness, awkward postures, force, additional factors, lack of recovery periods, duration of repetitive task.	Quantitative	Upper limb
OGRA checklist *	Mer. [11]. [41]	Semi-detailed method that considers, in a simplified way, the same risk factors as the OCRA index. Exposure level is classified in the three-zone system. Applicable also to multitask repetitive jobs.	Quantitative	Upper limb

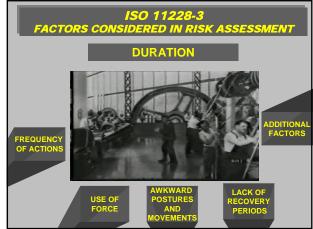


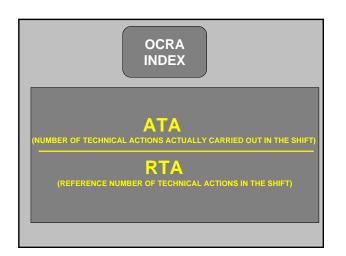




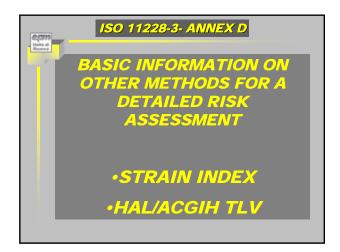
Whichever method is used for detailed risk assessment, it should allow to classify the risk by the 3-zone model (green; yellow; red) and to address the consequent action to be taken according to criteria given in Table 1.							
AREA	Table 1 — I RISK LEVEL	Method 2: Final assessment criteria CONSEQUENCES					
	NO RISK	Acceptable,					
GREEN	NORISK	no consequences.					
GREEN YELLOW	VERY LOW RISK						



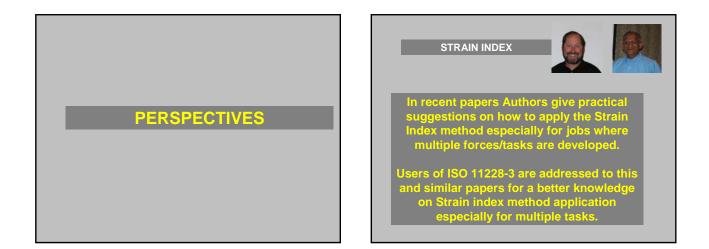


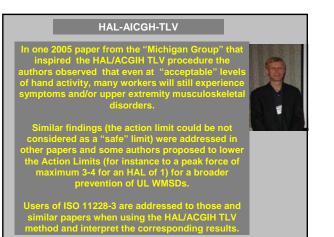


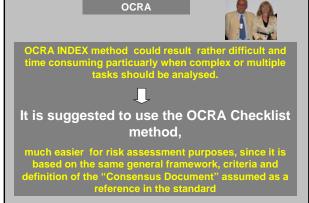
ZONE	OCRA VALUES	RISK LEVEL	CONSEQUENCES
GREEN	≰ 2.2	NO RISK. UL-WMSDs (PA) forecast is not significantly different from the one expected in the reference population.	Acceptable. No consequences
YELLOW	2.3 - 3.5	VERY LOW RISK. UL-WMSDs (PA) forecast is higher than previous but lower than twice the one expected in the reference population.	Advisable to set up improvemen with regard to structural risk factors (posture, force, technical actions, etc.) or to suggest other organizational measures.
RED	> 3.5	RISK. UL-WMSDs (PA) forecast Is higher than twice the one expected in the reference population. The higher the index, the higher the risk.	Redesign of tasks and workplace according to priorities is recommended.











OCRA

Updates on OCRA (Index and Checklist)

- <u>A "traditional" procedure</u> has been proposed, whose results could be defined as "time weighted average", It seems to be appropriate when considering rotations among tasks that are performed very frequently, for instance almost once every hour (or for shorter periods)
- 2. <u>A new procedure</u>, based on a more realistic concept that the most stressful task is the minimum starting point. It is more appropriate when rotation among repetitive tasks is less frequent (i.e. once every 1.5 or more hours).

The new procedure is actually esperimentally used also for evaluating multiple repetitive tasks with long term rotations (week; moonth; year).

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IN THE WEBSITE SOFTWARE AND TOOLS FOR USING OCRA METHODS (OCRA INDEX AND OCRA CHECKLIST) ALSO FOR MULTITASK ANALYSIS ARE FREELY AVAILABLE

ISO CD 12259 (Technical Report) Ergonomics – Application document for standards on manual handling (ISO 11228 – 1,2,3) and working postures (ISO 11226). The ISO (and CEN) groups are now going to produce "technical documents" that should facilitate the practical application of the ISO 11228 (and EN 1005) series <u>The ISO application document will contain the following:</u> • Detailed definition of field of application of different standards; •Key enters (simple parametric hazard identification) to different standards;

stanoaros; •Updates of classification systems in part 1 (lifting) and 2 (push/pull);

Updates of the main selected methods used in the standards with particular reference to multitask analysis of lifting and repetitive tasks;

tasks; •Reference to websites relevant for applying the standards.

